

Contributions to the theoretical study of variational inference and robustness

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PhD Defense
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- 1 Consistency of variational inference
 - Variational inference
 - Theoretical results
 - Examples
- 2 Online variational inference algorithms
 - Bayes & online learning
 - Online variational inference
 - Simulations
- 3 Robust MMD-based estimation
 - Robustness in statistics
 - MMD-based estimation
 - MMD-Bayes estimator

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Notations

Assume that we observe X_1, \dots, X_n i.i.d from $P_0 = P_{\theta_0}$ in a model $\{P_\theta, \theta \in \Theta\}$ with likelihood $L_n(\theta)$. Prior π on Θ .

The posterior

$$\pi_n(d\theta) \propto L_n(\theta)\pi(d\theta).$$

The tempered posterior - $0 < \alpha < 1$

$$\pi_{n,\alpha}(d\theta) \propto [L_n(\theta)]^\alpha \pi(d\theta).$$

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Computation of the posterior

The classical MCMC algorithms may be slow when both the model dimension and the sample size are large. A more and more popular alternative : **variational inference**.

Variational approximations : definition

Idea of VB : chose a family \mathcal{Q} of probability distributions on Θ and approximate $\pi_{n,\alpha}$ by a distribution in \mathcal{Q} :

$$\tilde{\pi}_{n,\alpha} := \arg \min_{q \in \mathcal{Q}} KL(q, \pi_{n,\alpha}).$$

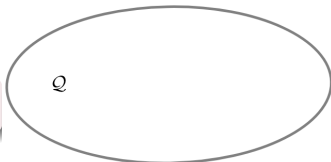
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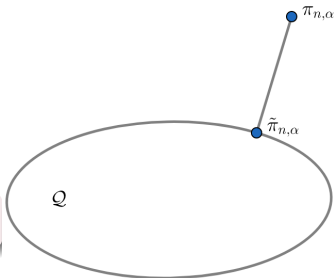
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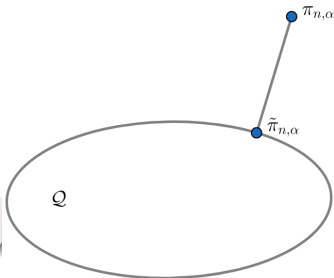
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Examples of sets \mathcal{Q} :

- parametric ($\Theta \subset \mathbb{R}^d$) :

$$\{ \mathcal{N}(\mu, \Sigma) : \mu \in \mathbb{R}^d, \Sigma \in \mathcal{S}_d^+ \}.$$

- mean-field ($\Theta = \Theta_1 \times \Theta_2$) :

$$q(d\theta) = q_1(d\theta_1) \times q_2(d\theta_2).$$

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Tools for the consistency of VB

The α -Rényi divergence for $\alpha \in (0, 1)$

$$D_\alpha(P, R) = \frac{1}{\alpha - 1} \log \int (dP)^\alpha (dR)^{1-\alpha}.$$

For $1/2 \leq \alpha$, link with Hellinger and Kullback :

$$\mathcal{H}^2(P, R) \leq D_\alpha(P, R) \xrightarrow[\alpha \nearrow 1]{} KL(P, R).$$

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Consistency at rate r_n

$$\mathbb{E} \left[\int D_\alpha(P_\theta, P_{\theta_0}) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq r_n \xrightarrow[n \rightarrow \infty]{} 0.$$

Technical condition for posterior consistency

Prior mass condition for consistency of tempered posteriors

The rate (r_n) is such that

$$\pi[\mathcal{B}(r_n)] \geq e^{-nr_n}$$

where $\mathcal{B}(r) = \{\theta \in \Theta : KL(P_{\theta_0}, P_{\theta}) \leq r\}$.

Prior mass condition for consistency of Variational Bayes

The rate (r_n) is such that there exists $q_n \in \mathcal{Q}$ such that

$$\int KL(P_{\theta_0}, P_{\theta}) q_n(d\theta) \leq r_n, \text{ and } KL(q_n, \pi) \leq nr_n.$$

Consistency of the approximate posterior

Theorem

Under the prior mass condition, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_{\alpha}(P_{\theta}, P_{\theta_0}) \pi_{n,\alpha}(d\theta) \right] \leq \frac{1 + \alpha}{1 - \alpha} r_n.$$

Theorem

Under the extended prior mass condition, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_{\alpha}(P_{\theta}, P_{\theta_0}) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq \frac{1 + \alpha}{1 - \alpha} r_n.$$

Misspecified case

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Under the extended prior mass condition, for any $\alpha \in (0, 1)$,

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Assume now that X_1, \dots, X_n i.i.d $\sim P_0 \notin \{P_\theta, \theta \in \Theta\}$.

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Theorem

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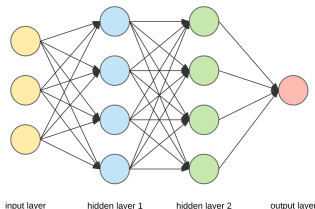
$$\mathbb{E} \left[\int D_\alpha(P_\theta, P_0) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq \frac{\alpha}{1 - \alpha} \inf_{\theta} KL(P_0, P_\theta) + \frac{1 + \alpha}{1 - \alpha} r_n.$$

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Nonparametric regression & Deep Neural Networks

Nonparametric regression

- $X_i \sim \mathcal{U}([-1, 1]^d)$,
- $Y_i = f_0(X_i) + \zeta_i$,
- $\zeta_i \sim \mathcal{N}(0, \sigma^2)$.



Deep neural networks

- Depth $L \geq 3$, width $D \geq d$, sparsity $S \leq T$.
- Parameter $\theta = \{(A_1, b_1), \dots, (A_L, b_L)\}$.
- $f_\theta(x) = A_L \rho(A_{L-1} \dots \rho(A_1 x + b_1) + \dots + b_{L-1}) + b_L$.

ReLU Deep Neural Networks : convergence rates

Theorem

Chose spike-and-slab prior and variational set on θ . Then :

$$\begin{aligned} \mathbb{E} \left[\int \|f_\theta - f_0\|_2^2 \tilde{\pi}_{n,\alpha}(d\theta) \right] \\ \leq \frac{2}{1-\alpha} \inf_{\theta^*} \|f_{\theta^*} - f_0\|_2^2 + \frac{2}{1-\alpha} \left(1 + \frac{\sigma^2}{\alpha} \right) r_n^{S,L,D}, \end{aligned}$$

with $r_n^{S,L,D} \sim \frac{S \log(nL/S)}{n} \vee \frac{LS \log D}{n}$.

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with $r_n^{S,L,D} \sim \frac{S \log(nL/S)}{n} \vee \frac{LS \log D}{n}$.

If f_0 β -Hölder for suitable (S, L, D) : $\tilde{O}\left(n^{-\frac{2\beta}{2\beta+d}}\right)$.

Related publications



B.-E. C.-A., P. Alquier. Consistency of Variational Bayes Inference for Estimation and Model Selection in mixtures. *Electronic Journal of Statistics*, 2018.



B.-E. C.-A. Consistency of ELBO Maximization for Model Selection. *Proceedings of AABI*, 2019.



B.-E. C.-A. Convergence Rates of Variational Inference in Sparse Deep Learning. *Accepted at ICML*, 2020.

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Online learning

Objective

Make sure that we learn to predict well as **fast as possible**.

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Keep, **without stochastic assumptions on the data**, as small as possible for any T :

$$\sum_{t=1}^T \ell(x_t; \theta_t).$$

The regret

$$R_T = \sum_{t=1}^T \ell(x_t; \theta_t) - \inf_{\theta \in \Theta} \sum_{t=1}^T \ell(x_t; \theta).$$

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What strategy can lead to a low regret ?

Online gradient algorithm (OGA)

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- θ_{t+1} is the solution of :

$$\min_{\theta} \left\{ \theta^T \sum_{s=1}^t \nabla_{\theta} \ell_s(\theta_s) + \frac{\|\theta - \theta_1\|^2}{2\alpha} \right\}$$

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and

$$\min_{\theta} \left\{ \theta^T \nabla_{\theta} \ell_t(\theta_t) + \frac{\|\theta - \theta_t\|^2}{2\alpha} \right\}.$$

Bayesian learning and VI

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- Bayesian inference / EWA :

$$\pi_{t+1,\alpha}(d\theta) \propto \exp\left(-\alpha \sum_{s=1}^t \ell_s(\theta_s)\right) \pi(d\theta).$$

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- **Equivalent online formulation for VI ?**

A regret bound for EWA

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Theorem

If the loss is bounded by B :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \pi_{t,\alpha}}[\ell_t(\theta)] \leq \inf_q \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim q}[\ell_t(\theta)] + \frac{\alpha B^2 T}{8} + \frac{KL(q, \pi)}{\alpha} \right\}.$$

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Under similar assumptions than in the batch case, that is, the prior gives enough mass to relevant θ , and $\alpha \sim 1/\sqrt{T}$,

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \pi_{t,\alpha}}[\ell_t(\theta)] \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + \mathcal{O}(\sqrt{dT \log(T)})$$

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Equivalent regret bounds for VI ?

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 - Simulations
- 3 Robust MMD-based estimation
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Variational approximations of EWA



B.-E. C.-A., P. Alquier & M. E. Khan. A Generalization Bound for Online Variational Inference. *Proceedings of ACML*, 2019.

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Parametric variational approximation :

$$\mathcal{Q} = \{q_{\mu}, \mu \in M\}.$$

Objective : propose a way to update $\mu_t \rightarrow \mu_{t+1}$ so that q_{μ_t} leads to similar performances as $\pi_{t,\alpha}$ in EWA...

SVA and SVB strategies

- SVA (Sequential Variational Approximation) :

$$\mu_{t+1} = \arg \min_{\mu \in M} \left\{ \sum_{s=1}^t \mathbb{E}_{\theta \sim q_{\mu}} [\ell_s(\theta)] + \frac{KL(q_{\mu}, \pi)}{\alpha} \right\}.$$

- SVB (Streaming Variational Bayes) :

SVA and SVB strategies

- SVA (Sequential Variational Approximation) :

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An example : SVB with Gaussian approximations

As an example, assume that $\theta \in \mathbb{R}^d$, the prior is $\pi = \mathcal{N}(0, s^2 I)$ and that we use the variational approximation

$$\text{family : } q_\mu = q_{m,\sigma} = \mathcal{N} \left(m, \begin{pmatrix} \sigma_1^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_d^2 \end{pmatrix} \right).$$

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In this case, the update in SVB is :

$$\begin{aligned} m_{t+1} &= m_t - \alpha \sigma_t^2 \odot \nabla_{m=m_t} \mathbb{E}_{\theta \sim q_{m_t, \sigma_t}} [\ell_t(\theta)] \\ \sigma_{t+1} &= \sigma_t \odot h \left(\frac{\alpha \sigma_t \nabla_{\sigma=\sigma_t} \mathbb{E}_{\theta \sim q_{m_t, \sigma_t}} [\ell_t(\theta)]}{2} \right) \end{aligned}$$

where \odot means “componentwise multiplication” and $h(x) = \sqrt{1 + x^2} - x$ is also applied componentwise.

A regret bound for SVA

Theorem

Assume that the expected loss $\mu \rightarrow \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$ is L -Lipschitz and convex.

A regret bound for SVA

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Assume that the expected loss $\mu \rightarrow \mathbb{E}_{\theta \sim q_\mu}[\ell_t(\theta)]$ is L -Lipschitz and convex. (this is for example the case as soon as the loss $\ell_t(\theta)$ is convex in θ and L -Lipschitz, and μ is a location-scale parameter).

A regret bound for SVA

Theorem

Assume that the expected loss $\mu \rightarrow \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$ is L -Lipschitz and convex. Assume that $\mu \mapsto KL(q_\mu, \pi)$ is γ -strongly convex. Then SVA satisfies :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \leq \inf_{q_\mu} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)] + \frac{\alpha L^2 T}{\gamma} + \frac{KL(q_\mu, \pi)}{\alpha} \right\}.$$

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Application to Gaussian approximation leads to :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + (1 + o(1)) \frac{2L}{\gamma} \sqrt{dT \log(T)}.$$

For SVB : some results in the Gaussian case.

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Test on the Forest Cover Type dataset

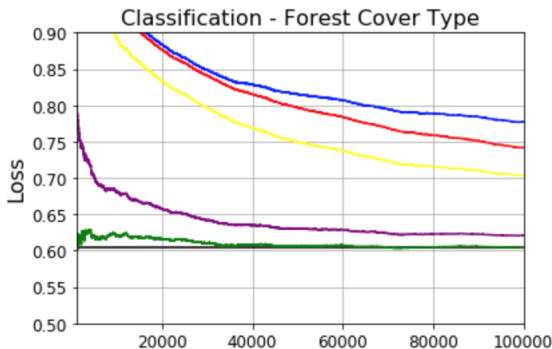


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Test on the Boston Housing dataset

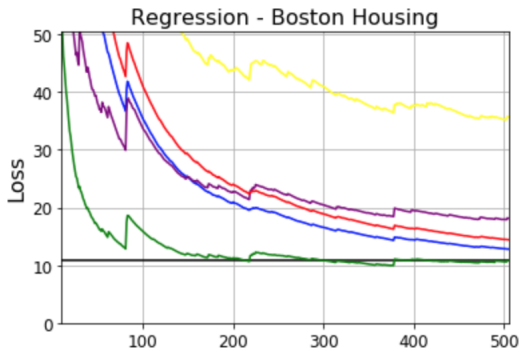


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

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 - Examples
- 2 Online variational inference algorithms
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 - Simulations
- 3 Robust MMD-based estimation
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Many popular estimators in statistics such as MLE do not satisfy these requirements in some settings.

A typical example

Yatracos' skeleton estimate $\hat{\theta}_n^Y$:

$$\mathbb{E} \left[d_{TV}(P_{\hat{\theta}_n^Y}, P_0) \right] \leq 3d_{TV}(P_0, P_{\theta_0}) + C \cdot \sqrt{\frac{\dim(\Theta)}{n}}$$

where

$$d_{TV}(P, Q) = \sup_E |P(E) - Q(E)|.$$



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Additional requirement : an estimator must be tractable!!!

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Maximum Mean Discrepancy

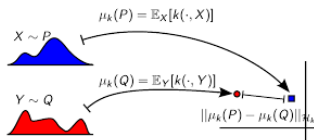
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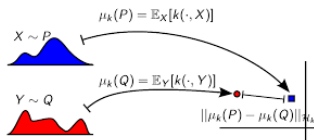


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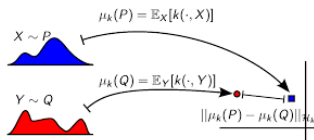
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Definition : the MMD distance

$$\mathbb{D}_k(P, Q) = \|\mu_k(P) - \mu_k(Q)\|_{\mathcal{H}_k}.$$

MMD-based estimator

X_1, \dots, X_n be i.i.d in \mathcal{X} from a probability distribution P_0 ,
model $\{P_\theta, \theta \in \Theta\}$, bounded p.d. kernel $0 \leq k(x, y) \leq 1$.

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$$\hat{\theta}_n = \arg \min_{\theta \in \Theta} \mathbb{D}_k \left(P_\theta, \hat{P}_n \right) \quad \text{where } \hat{P}_n = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}.$$

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Theorem

$$\forall P_0, \quad \mathbb{E} [\mathbb{D}_k(P_{\hat{\theta}_n}, P_0)] \leq \underbrace{\inf_{\theta \in \Theta} \mathbb{D}_k(P_\theta, P_0)}_{\substack{\leq 2\varepsilon \text{ when} \\ P_0 = (1 - \varepsilon)P_{\theta_0} + \varepsilon Q}} + \frac{2}{\sqrt{n}}.$$

How to compute $\hat{\theta}_n^{MMD}$?

We actually have (up to a constant)

$$\mathbb{D}_k^2(P_\theta, \hat{P}_n) = \mathbb{E}_{X, X' \sim P_\theta} [k(X, X')] - \frac{2}{n} \sum_{i=1}^n \mathbb{E}_{X \sim P_\theta} [k(X_i, X)]$$

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and so

$$\begin{aligned} & \nabla_\theta \mathbb{D}_k^2(P_\theta, \hat{P}_n) \\ &= 2 \mathbb{E}_{X, X' \sim P_\theta} \left\{ \left[k(X, X') - \frac{1}{n} \sum_{i=1}^n k(X_i, X) \right] \nabla_\theta [\log p_\theta(X)] \right\} \end{aligned}$$

that can be approximated by sampling from P_θ .

Example : Gaussian mean estimation

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Using a Gaussian kernel $k(x, y) = \exp(-(x - y)^2/2)$, from the previous theorem and from the equality

$$\mathbb{D}_k^2(P_\theta, P_{\theta'}) = \sqrt{2} \left[1 - \exp\left(-\frac{(\theta - \theta')^2}{4\sigma^2}\right) \right]$$

we obtain

$$\mathbb{E} \left[(\hat{\theta}_n - \theta_0)^2 \right] \leq 16\sigma^2 \left(\varepsilon^2 + \frac{1}{n} \right).$$

(for $\varepsilon^2 + \frac{1}{n} \leq \frac{1}{4\sqrt{2}}$).

Example : Gaussian mean estimation, simulations

Model : $\mathcal{N}(\theta, 1)$, and X_1, \dots, X_n i.i.d $\mathcal{N}(\theta_0, 1)$, $n = 100$ and we repeat the experiment 200 times.

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Now, $\varepsilon = 1\%$ are replaced by 1000.

mean absolute error	10.018	0.0903
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Bayesian MMD-based estimation

Given a prior $\pi(\theta)$ we propose the following pseudo-posterior :

$$\pi_n^\beta(d\theta) \propto \exp\left(-\beta \mathbb{D}_k^2(P_\theta, \hat{P}_n)\right) \pi(d\theta).$$

Theorem

Let $\mathcal{B} = \{\theta \in \Theta / \mathbb{D}_k(P_{\theta_0}, P_\theta) \leq 1/\sqrt{n}\}$. Assume (π, β) satisfies the prior mass condition : $\pi(\mathcal{B}) \geq e^{-\beta/\sqrt{n}}$. Then :

$$\mathbb{E} \left[\int \mathbb{D}_k^2(P_\theta, P_0) \pi_n^\beta(d\theta) \right] \leq 8 \inf_{\theta \in \Theta} \mathbb{D}_k^2(P_\theta, P_0) + \frac{16}{n}.$$

We also prove similar results for variational approximations, that can be computed by stochastic gradient descent :

$$q_\beta = \arg \min_{q \in \mathcal{Q}} \left\{ \mathbb{E}_{\theta \sim q} \left[\mathbb{D}_k^2(P_\theta, \hat{P}_n) \right] + \frac{\text{KL}(q, \pi)}{\beta} \right\}.$$

Related publications



B.-E. C.-A., P. Alquier. Finite sample properties of parametric MMD estimation : robustness to misspecification and dependence. *Preprint ArXiv*, 2019.



B.-E. C.-A., P. Alquier. MMD-Bayes : Robust Bayesian Estimation via Maximum Mean Discrepancy. *Proceedings of AABI*, 2020.

Thank you !